

Original paper: (on NIPS 2017)
Improved Graph Laplacian via Geometric Consistency
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The task

Problem: Estimate the radius r of heat kernel in manifold embedding

Formally: Optimize Laplacian w.r.t. parameters (e.g. radius r)

Previous work:

- asymptotic rates depending on the (unknown) manifold [4]
- Embedding dependent neighborhood reconstruction [6]

Challenge: it's an unsupervised problem! What "target" to choose?

The radius r affects...

- Quality of manifold embedding via neighborhood selection
- Laplacian-based embedding and clustering via the kernel for computing similarities
- Estimation of other geometric quantities that depend on the Laplacian (e.g Riemannian metric) or not (e.g intrinsic dimension).
- Regression on manifolds via Gaussian Processes or Laplacian regularization.

Heat Kernels, Laplacians, and Geometry

- Heat Kernel

$$W_{ij} = \exp\left(-\frac{\|x_i - x_j\|^2}{r^2}\right)$$

- Radius parameter: r
- Compute the Graph Laplacian:

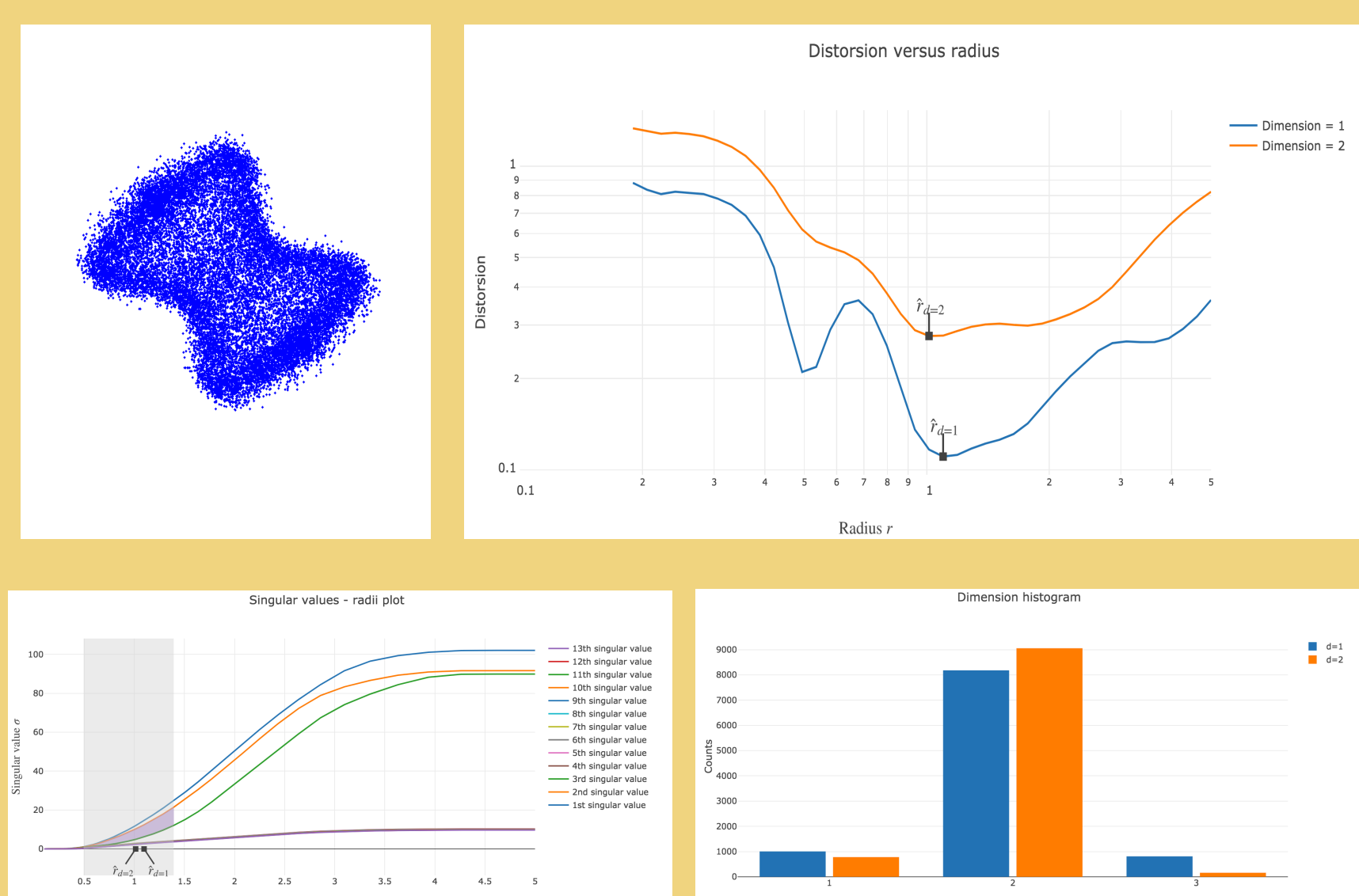
$$t_i = \sum_j W_{ij}, \quad W'_{ij} = \frac{W_{ij}}{t_i t_j}, \quad t'_i = \sum_j W'_{ij}$$

- Then

$$L = \sum_j \frac{W'_{ij}}{t'_j}$$

- Assume a Riemannian Manifold (\mathcal{M}, g)
- Riemannian Metric, g , encodes geometry e.g. volume element is $\sqrt{\det G(X)}$
- $(H(p))_{kj} = \frac{1}{2} \Delta_{\mathcal{M}}(x^k - x^k(p))(x^i - x^i(p))|_{x=x(p)}$
- Optimize r for geometric consistency

Using \hat{r} for dimension estimation (with [5])



- Intrinsic dimension is estimated by the eigengap of Local SVD with radius \hat{r} .
- Upper left: hourglass data
- Upper right: \hat{r} estimates as the minimizer of distortion.
- Lower left: avg. singular values versus radii.
- Lower right: histogram of estimated dimensions on each points.

GC Algorithm: Optimizing the Laplacian

Input Data $\{x_1, x_2, \dots, x_N\}$, dimension d' , $\text{pow}=1, -1$

For each ϵ

1. Estimate the Laplacian induced by r
2. For each data point x_i (in a subsample)
 1. Weights $w_j = K_r(x_i, x_j)$ for all x_j
 2. Project neighbors of x_i on tangent subspace

Algorithm 2 Tangent Subspace Projection(X, w, d')

Input: $N \times r$ design matrix X , weight vector w , working dimension d'
 Compute Z using (6)
 $[V, \Lambda] \leftarrow \text{eig}(Z^T Z, d')$ (i.e. d' -SVD of Z)
 Center X around \bar{x} from (6)
 $Y \leftarrow X V_{:,1:d'}$ (Project X on d' principal subspace)
return Y

3. Treat Y as an embedding of X . Estimate the R. metric for Y

Algorithm 1 Riemannian Metric($X, i, L, \text{pow} \in \{-1, 1\}$)

Input: $N \times d$ design matrix X , i index in data set, Laplacian L , binary variable pow
for $k = 1 \rightarrow d, l = 1 \rightarrow d$ **do**
 $H_{k,l} \leftarrow \sum_{j=1}^N L_{ij} (X_{jk} - X_{ik})(X_{jl} - X_{il})$
end for
return H^{pow} (i.e. H if $\text{pow} = 1$ and H^{-1} if $\text{pow} = -1$)

4. But Y should be isometric to X . Hence H should be the identity matrix. Penalize the difference.

Algorithm 3 Compute Distortion(X, ϵ, d')

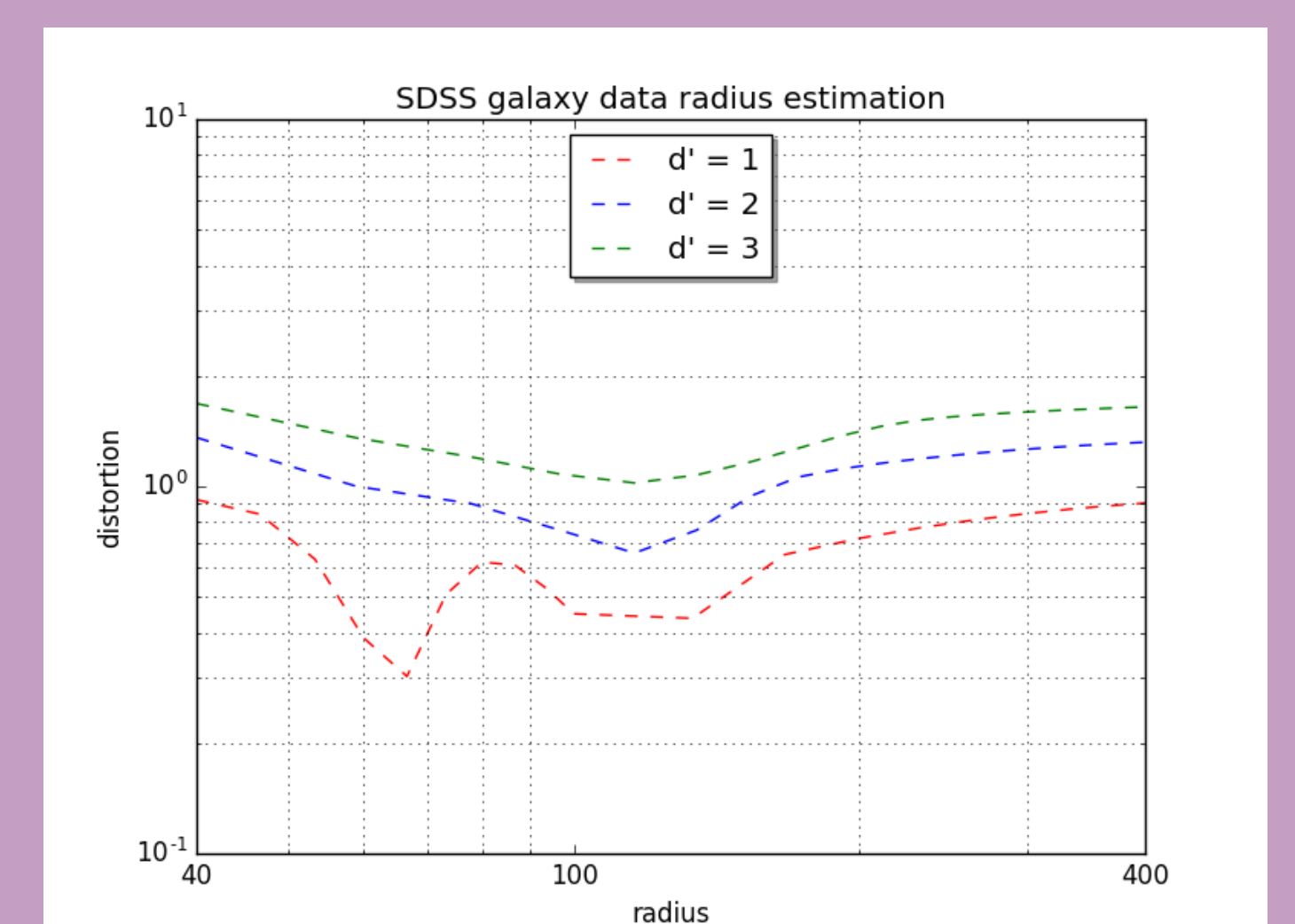
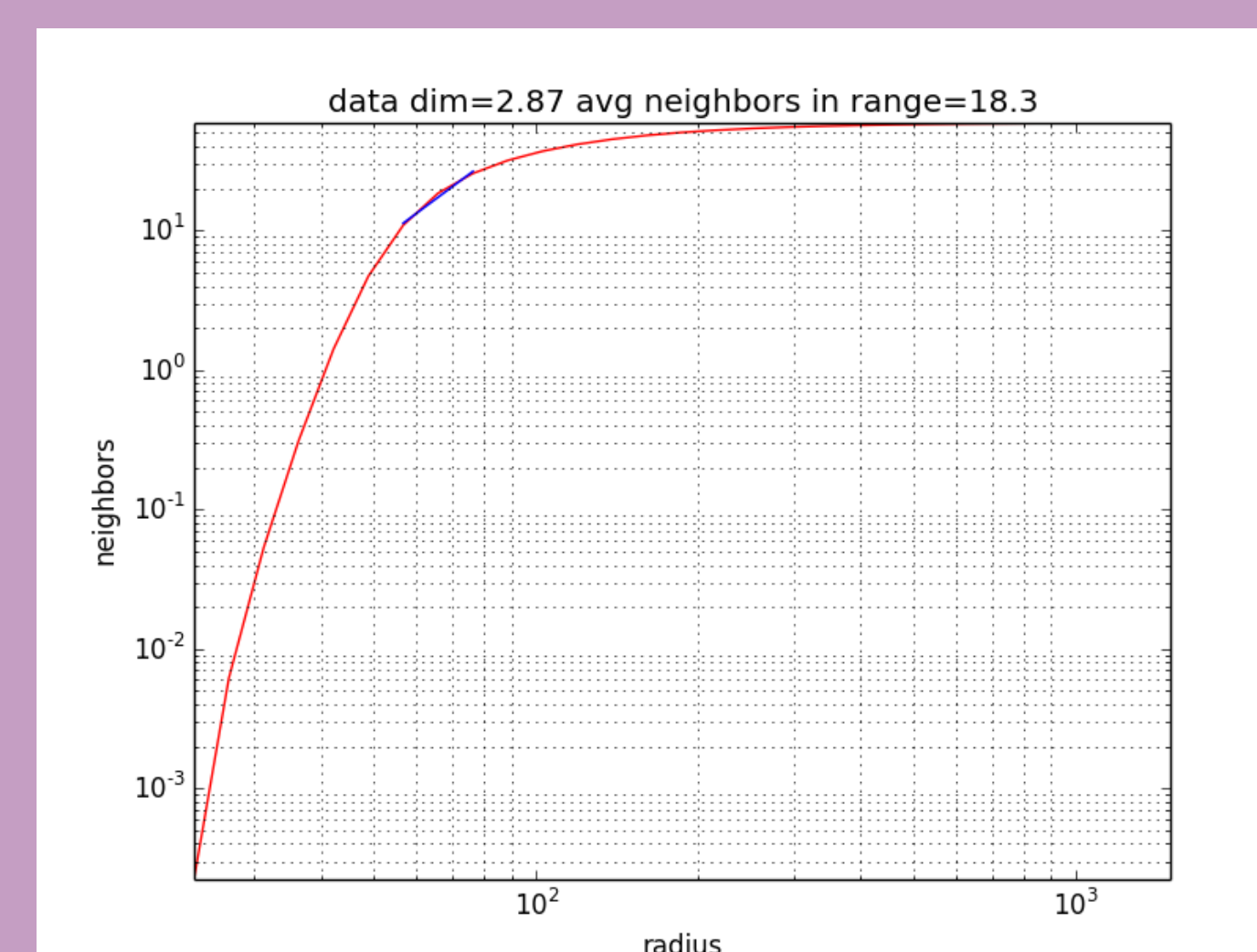
Input: $N \times r$ design matrix X , ϵ , working dimension d' , index set $\mathcal{I} \subseteq \{1, \dots, N\}$
 Compute the heat kernel W by (2) for each pair of points in X
 Compute the graph Laplacian L from W by (3)
 $D \leftarrow 0$
for $i \in \mathcal{I}$ **do**
 $Y \leftarrow \text{TangentSubspaceProjection}(X, W_{i,:}, d')$
 $H \leftarrow \text{RiemannianMetric}(Y, L, \text{pow} = 1)$
 $D \leftarrow D + \frac{\|H - I_{d'}\|^2}{|\mathcal{I}|}$
end for
return D

Measures departure from isometry, i.e. geometric consistency

Output \hat{r} that minimizes distortion D

\hat{r} for embedding Spectra of galaxies

$N=670,000$, $r=3750$ dimensions (www.sdss.org)



Radius Estimate for Galaxy Spectra.

Left: GC results for $d' = 1, 2, 3$; $3 \cdot r^{\text{opt}} = 66$

Right: log-log plot of radius vs avg. # nbrs;

Indicates $d=3$ at $r^{\text{opt}} = 22$

Conclusions: Geometry Consistency (GC) is...

- Choosing the correct radius/bound/scale is important in any non-linear dimension reduction task1.
- The GC Algorithm required minimal knowledge:
 - maximum radius, minimum radius,
 - (optionally: dimension d of the manifold.)
- The chosen radius can be used in
 - any embedding algorithm
 - semi-supervised learning with Laplacian Regularizer (see our NIPS 2017 paper)
 - estimating dimension d (as shown here)

References

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